

The likelihood approach to statistical decision problems

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 - ▶ likelihood function (here λ)
 - ▶ loss function (here W)
- ▶ **statistical model:** $(\Omega, \mathcal{F}, P_\theta)$ with $\theta \in \Theta$ (where Θ is a nonempty set) and random variables $X_i : \Omega \rightarrow \mathcal{X}_i$

loss function

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$$W : \Theta \times \mathcal{D} \rightarrow [0, +\infty),$$

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 - ▶ hypothesis testing: **likelihood** ratio tests

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- ▶ most successful general methods:
 - ▶ point estimation: maximum **likelihood** estimators
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- ▶ these methods do not fit well in the setting of classical or Bayesian decision theory: [here](#) they are unified (and generalized) in **likelihood** decision theory

simple decision example

- ▶ random sample of 3 black balls from an urn containing 100 balls, of which $\theta \in \Theta = \{50, 99, 100\}$ are black: select $d \in \mathcal{D} = \{\text{"50"}, \text{"not 50"}\}$

W	"50"	"not 50"	λ
50	0	15	0.12
99	1	0	0.97
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- ▶ $\lambda_x : \Theta \rightarrow [0, 1]$ is the (relative) likelihood function given $X = x$, when

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- ▶ prior information can be described by a prior likelihood function: if X_1 and X_2 are independent, then $\lambda_{(x_1, x_2)} \propto \lambda_{x_1} \lambda_{x_2}$ (i.e., when $X_2 = x_2$ is observed, the prior λ_{x_1} is updated to the posterior $\lambda_{(x_1, x_2)}$)

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- ▶ strong similarity with the Bayesian approach (both satisfy the likelihood principle): a fundamental advantage of the likelihood approach is the possibility of not using prior information (since $\lambda_{x_1} \equiv 1$ describes complete ignorance)

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 - ▶ $W(\cdot, H_1) = c I_{\mathcal{H}_0}$ and $W(\cdot, H_0) = c' I_{\mathcal{H}_1}$ with $c \geq c'$
 - ▶ MPL decision: **likelihood ratio test** $\Lambda(\mathcal{H}_0) \geq \frac{c'}{c}$

simple estimation example

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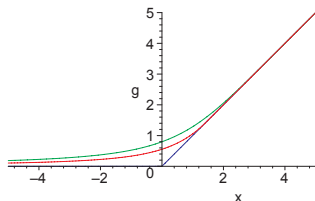
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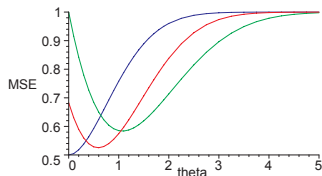
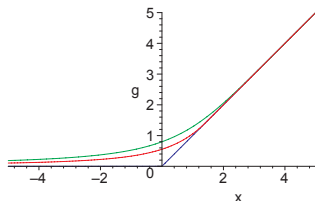
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 - ▶ **parametrization invariance**: $b : \Theta \rightarrow \Theta$ bijection $\Rightarrow V(w \circ b, \lambda \circ b) = V(w, \lambda)$

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- ▶ **likelihood decision function**: $\delta : \mathcal{X} \rightarrow \mathcal{D}$ such that $\delta(x)$ minimizes $V(W(\cdot, d), \lambda_x)$ for all $x \in \mathcal{X}$

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 - ▶ **asymptotic efficiency**: under slightly stronger regularity conditions, the above convergence is as fast as possible

example: estimation of variance components

- ▶ estimation of the variance components in the 3×3 random effect one-way layout, under normality assumptions and weighted squared error loss

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- ▶ normality assumptions:

$$\alpha_i \sim \mathcal{N}(0, v_a), \quad \varepsilon_{ij} \sim \mathcal{N}(0, v_e), \quad \text{all independent}$$

$$\Rightarrow X_{ij} \sim \mathcal{N}(\mu, v_a + v_e) \quad \text{dependent}, \quad \theta = (\mu, v_a, v_e) \in \mathbb{R} \times (0, \infty)^2$$

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- ▶ estimates \widehat{v}_e and \widehat{v}_a of variance components v_e and v_a are functions of

$$SS_e = \sum_{i=1}^3 \sum_{j=1}^3 (x_{ij} - \bar{x}_{i.})^2 \quad \text{and} \quad SS_a = 3 \sum_{i=1}^3 (\bar{x}_{i.} - \bar{x}_{..})^2,$$

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$$\frac{SS_e}{v_e} \sim \chi_6^2, \quad \text{and} \quad \frac{\frac{1}{3} SS_a}{v_a + \frac{1}{3} v_e} \sim \chi_2^2$$

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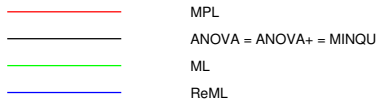
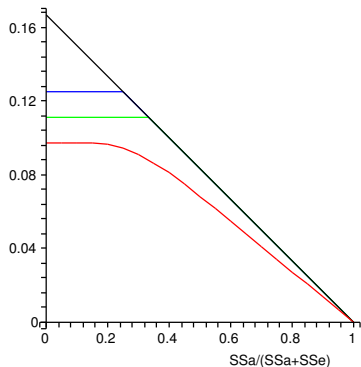
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- ▶ invariant loss functions:

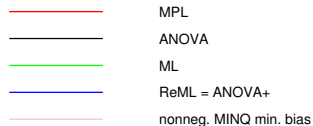
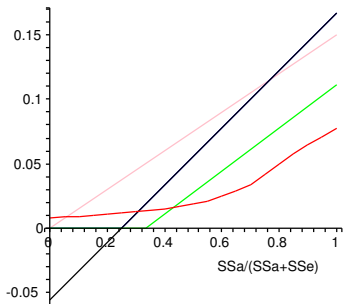
$$W(\theta, \hat{v}_e) = 3 \frac{(v_e - \hat{v}_e)^2}{v_e^2} \quad \text{and} \quad W(\theta, \hat{v}_a) = \frac{(v_a - \hat{v}_a)^2}{(v_a + \frac{1}{3} v_e)^2}$$

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$$\frac{\widehat{v}_e}{SS_a + SS_e}$$

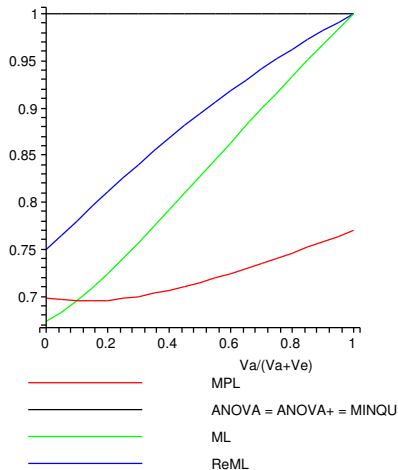


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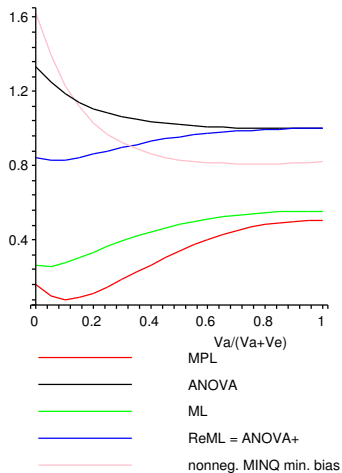


example: estimation of variance components

$$3 \frac{E[(\widehat{v}_e - v_e)^2]}{v_e^2}$$



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 - ▶ is consistent and asymptotically efficient
 - ▶ does not need prior information

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