

# Updating and avoiding sure loss

Marco Cattaneo

Department of Physics and Mathematics, University of Hull

WPMSIIP 2014, Ghent, Belgium

9 September 2014

# introduction

updating rules	Bayesian	coherent	$\alpha$ -cut
continuity	✓	✗	✓
vacuous priors	✗	✗	✓
iterative consistency	✓	✓	✗
coherence	✓	✓	✗

## updating rules

- ▶ when an event  $B \subset \Omega$  is observed, previsions must be updated

## updating rules

- ▶ when an event  $B \subset \Omega$  is observed, previsions must be updated
- ▶ Bayesian updating of linear previsions  $P$  with  $P(B) > 0$ :

$$P \mapsto P(\cdot | B) \quad \text{with} \quad P(X | B) = \frac{P(X I_B)}{P(B)} \quad \text{for all bounded } X : \Omega \rightarrow \mathbb{R}$$

## updating rules

- ▶ when an event  $B \subset \Omega$  is observed, previsions must be updated
- ▶ Bayesian updating of linear previsions  $P$  with  $P(B) > 0$ :

$$P \mapsto P(\cdot | B) \quad \text{with} \quad P(X | B) = \frac{P(X I_B)}{P(B)} \quad \text{for all bounded } X : \Omega \rightarrow \mathbb{R}$$

- ▶ generalizations of Bayesian updating to (coherent) lower previsions  $\underline{P}$  with  $\underline{P}(B) > 0$ :

## updating rules

- ▶ when an event  $B \subset \Omega$  is observed, previsions must be updated
- ▶ Bayesian updating of linear previsions  $P$  with  $P(B) > 0$ :

$$P \mapsto P(\cdot | B) \quad \text{with} \quad P(X | B) = \frac{P(X I_B)}{P(B)} \quad \text{for all bounded } X : \Omega \rightarrow \mathbb{R}$$

- ▶ generalizations of Bayesian updating to (coherent) lower previsions  $\underline{P}$  with  $\underline{P}(B) > 0$ :
  - ▶ regular extension:

$$\underline{P} \mapsto \inf_{P \geq \underline{P}, P(B) > 0} P(\cdot | B)$$

# updating rules

- ▶ when an event  $B \subset \Omega$  is observed, previsions must be updated
- ▶ Bayesian updating of linear previsions  $P$  with  $P(B) > 0$ :

$$P \mapsto P(\cdot | B) \quad \text{with} \quad P(X | B) = \frac{P(X I_B)}{P(B)} \quad \text{for all bounded } X : \Omega \rightarrow \mathbb{R}$$

- ▶ generalizations of Bayesian updating to (coherent) lower previsions  $\underline{P}$  with  $\underline{P}(B) > 0$ :

- ▶ regular extension:

$$\underline{P} \mapsto \inf_{P \geq \underline{P}, P(B) > 0} P(\cdot | B)$$

- ▶  $\alpha$ -cut rule, where  $\alpha \in (0, 1)$ :

$$\underline{P} \mapsto \inf_{P \geq \underline{P}, P(B) \geq \alpha \bar{P}(B)} P(\cdot | B)$$

# continuity

- ▶ Bayesian updating is continuous with respect to the metric

$$d(P, P') = \sup_{X: \Omega \rightarrow [-1, 1]} |P(X) - P'(X)|$$



# continuity

- ▶ Bayesian updating is continuous with respect to the metric

$$d(P, P') = \sup_{X: \Omega \rightarrow [-1, 1]} |P(X) - P'(X)|$$

- ▶  $\alpha$ -cut updating is continuous with respect to the (Hausdorff) metric

$$d(\underline{P}, \underline{P}') = \sup_{X: \Omega \rightarrow [-1, 1]} |\underline{P}(X) - \underline{P}'(X)|$$

for all  $\alpha \in (0, 1)$ , while regular/natural/coherent updating has discontinuities at points  $\underline{P}$  with  $\overline{P}(B) > \underline{P}(B) = 0$  (Cattaneo, 2014)

## vacuous priors

- ▶ contrary to linear previsions, lower previsions can describe prior ignorance about the unknowns of a statistical model

## vacuous priors

- ▶ contrary to linear previsions, lower previsions can describe prior ignorance about the unknowns of a statistical model
- ▶ contrary to regular/natural/coherent updating, the  $\alpha$ -cut rule can update vacuous priors to non-vacuous posteriors in statistical analyses

## vacuous priors

- ▶ contrary to linear previsions, lower previsions can describe prior ignorance about the unknowns of a statistical model
- ▶ contrary to regular/natural/coherent updating, the  $\alpha$ -cut rule can update vacuous priors to non-vacuous posteriors in statistical analyses
- ▶ for regular statistical models, the imprecise previsions obtained from vacuous priors by means of  $\alpha$ -cut updating are **confidence intervals** with (asymptotic) level  $F_{\chi^2}(-2 \ln \alpha)$  (Wilks, 1938)

## iterative consistency

- ▶ Bayesian updating is iteratively consistent:

$$P((\cdot | B) | C) = P(\cdot | B \cap C) = P((\cdot | C) | B)$$

## iterative consistency

- ▶ Bayesian updating is iteratively consistent:

$$P((\cdot | B) | C) = P(\cdot | B \cap C) = P((\cdot | C) | B)$$

- ▶ contrary to regular/natural updating, the  $\alpha$ -cut rule is not iteratively consistent in general

# iterative consistency

- ▶ Bayesian updating is iteratively consistent:

$$P((\cdot | B) | C) = P(\cdot | B \cap C) = P((\cdot | C) | B)$$

- ▶ contrary to regular/natural updating, the  $\alpha$ -cut rule is not iteratively consistent in general
- ▶ this can be remedied by recording the whole (second-order) likelihood function  $lik(P) \propto P(\text{observations})$  as the second level of a **hierarchical model** (Cattaneo, 2008)

## iterative consistency

- ▶ Bayesian updating is iteratively consistent:

$$P((\cdot | B) | C) = P(\cdot | B \cap C) = P((\cdot | C) | B)$$

- ▶ contrary to regular/natural updating, the  $\alpha$ -cut rule is not iteratively consistent in general
- ▶ this can be remedied by recording the whole (second-order) likelihood function  $lik(P) \propto P(\text{observations})$  as the second level of a **hierarchical model** (Cattaneo, 2008)
- ▶ the  $\alpha$ -cut is then a way of obtaining lower previsions from the hierarchical model



## coherence

- ▶ contrary to Bayesian and regular/natural/coherent updating, the  $\alpha$ -cut rule does not avoid sure loss in general

## coherence

- ▶ contrary to Bayesian and regular/natural/coherent updating, the  $\alpha$ -cut rule does not avoid sure loss in general
- ▶ example:

$$\begin{aligned} X &\sim \text{Bernoulli}\left(\frac{1}{2}\right) \\ (Y | X = 0) &\sim \text{uniform on } \{1, \dots, n\} \\ (Y | X = 1) &\sim \text{vacuous on } \{1, \dots, n\} \end{aligned}$$

## coherence

- ▶ contrary to Bayesian and regular/natural/coherent updating, the  $\alpha$ -cut rule does not avoid sure loss in general
- ▶ example:

$$\begin{aligned}X &\sim \text{Bernoulli}\left(\frac{1}{2}\right) \\(Y | X = 0) &\sim \text{uniform on } \{1, \dots, n\} \\(Y | X = 1) &\sim \text{vacuous on } \{1, \dots, n\}\end{aligned}$$

- ▶ regular/natural/coherent updating:

$$\underline{P}(X = 1 | Y) = 0 \quad \text{and} \quad \bar{P}(X = 1 | Y) = \frac{n}{n+1} \quad (\text{dilation})$$

## coherence

- ▶ contrary to Bayesian and regular/natural/coherent updating, the  $\alpha$ -cut rule does not avoid sure loss in general
- ▶ example:

$$\begin{aligned}X &\sim \text{Bernoulli}\left(\frac{1}{2}\right) \\(Y | X = 0) &\sim \text{uniform on } \{1, \dots, n\} \\(Y | X = 1) &\sim \text{vacuous on } \{1, \dots, n\}\end{aligned}$$

- ▶ regular/natural/coherent updating:

$$\underline{P}(X = 1 | Y) = 0 \quad \text{and} \quad \bar{P}(X = 1 | Y) = \frac{n}{n+1} \quad (\text{dilation})$$

- ▶  $\alpha$ -cut updating:

$$\underline{P}(X = 1 | Y) = \left(1 - \frac{1}{(n+1)\alpha}\right) \vee 0 \xrightarrow{n \rightarrow \infty} 1 \quad (\text{sure loss})$$

## conclusion

- ▶ the relative importance of properties like coherence, continuity, and ability of using vacuous priors depends on the application field and on the exact interpretation of imprecise probabilities

## conclusion

- ▶ the relative importance of properties like coherence, continuity, and ability of using vacuous priors depends on the application field and on the exact interpretation of imprecise probabilities
- ▶  $\alpha$ -cut updating can be seen as a continuous approximation of coherent updating, but as a general approach it is only reasonable when the whole (second-order) likelihood function is recorded (iterative consistency)

## conclusion

- ▶ the relative importance of properties like coherence, continuity, and ability of using vacuous priors depends on the application field and on the exact interpretation of imprecise probabilities
- ▶  $\alpha$ -cut updating can be seen as a continuous approximation of coherent updating, but as a general approach it is only reasonable when the whole (second-order) likelihood function is recorded (iterative consistency)
- ▶ no (reasonable) method using the second-order likelihood function to obtain lower previsions can avoid sure loss in general

## references

- Cattaneo, M. (2008). Fuzzy probabilities based on the likelihood function. In *Soft Methods for Handling Variability and Imprecision*. Springer, 43–50.
- Cattaneo, M. (2014). A continuous updating rule for imprecise probabilities. In *Information Processing and Management of Uncertainty in Knowledge-Based Systems, Part 3*. Springer, 426–435.
- Wilks, S. S. (1938). The large-sample distribution of the likelihood ratio for testing composite hypotheses. *Ann. Math. Stat.* 9, 60–62.