

The likelihood approach to statistics as a theory of imprecise probability

Marco Cattaneo
Department of Statistics, LMU Munich
cattaneo@stat.uni-muenchen.de

September 11, 2009

likelihood function

- ▶ set \mathcal{P} of probability measures on (Ω, \mathcal{A})

likelihood function

- ▶ set \mathcal{P} of probability measures on (Ω, \mathcal{A})
- ▶ each $P \in \mathcal{P}$ is interpreted as a probabilistic model of the reality under consideration

likelihood function

- ▶ set \mathcal{P} of probability measures on (Ω, \mathcal{A})
- ▶ each $P \in \mathcal{P}$ is interpreted as a probabilistic model of the reality under consideration
- ▶ after having observed the event $A \in \mathcal{A}$, the **likelihood function** $lik(P) \propto P(A)$ on \mathcal{P} describes the *relative* ability of the models to forecast the observed data

likelihood function

- ▶ set \mathcal{P} of probability measures on (Ω, \mathcal{A})
- ▶ each $P \in \mathcal{P}$ is interpreted as a probabilistic model of the reality under consideration
- ▶ after having observed the event $A \in \mathcal{A}$, the **likelihood function** $lik(P) \propto P(A)$ on \mathcal{P} describes the *relative* ability of the models to forecast the observed data
- ▶ $\log \frac{lik(P_1)}{lik(P_2)}$ is the *information for discrimination* (or *weight of evidence*) in favor of P_1 against P_2

likelihood function

- ▶ set \mathcal{P} of probability measures on (Ω, \mathcal{A})
- ▶ each $P \in \mathcal{P}$ is interpreted as a probabilistic model of the reality under consideration
- ▶ after having observed the event $A \in \mathcal{A}$, the **likelihood function** $lik(P) \propto P(A)$ on \mathcal{P} describes the *relative* ability of the models to forecast the observed data
- ▶ $\log \frac{lik(P_1)}{lik(P_2)}$ is the *information for discrimination* (or *weight of evidence*) in favor of P_1 against P_2
- ▶ in particular, a constant lik describes the case of **no information** for discrimination among the probabilistic models in \mathcal{P}

hierarchical model

- ▶ the set \mathcal{P} of probability measures and the likelihood function lik on \mathcal{P} can be interpreted as the two levels of a **hierarchical model** of the reality under consideration

hierarchical model

- ▶ the set \mathcal{P} of probability measures and the likelihood function lik on \mathcal{P} can be interpreted as the two levels of a **hierarchical model** of the reality under consideration
- ▶ when an event $A \in \mathcal{A}$ is observed, the hierarchical model can be updated as follows:

$$\mathcal{P} \rightsquigarrow \mathcal{P}' = \{P(\cdot | A) : P \in \mathcal{P}, P(A) > 0\}$$

$$lik \rightsquigarrow lik'(P') \propto \sup_{P \in \mathcal{P} : P(\cdot | A) = P'} lik(P) P(A) \quad \text{on } \mathcal{P}'$$

hierarchical model

- ▶ the set \mathcal{P} of probability measures and the likelihood function lik on \mathcal{P} can be interpreted as the two levels of a **hierarchical model** of the reality under consideration
- ▶ when an event $A \in \mathcal{A}$ is observed, the hierarchical model can be updated as follows:

$$\mathcal{P} \rightsquigarrow \mathcal{P}' = \{P(\cdot | A) : P \in \mathcal{P}, P(A) > 0\}$$

$$lik \rightsquigarrow lik'(P') \propto \sup_{P \in \mathcal{P} : P(\cdot | A) = P'} lik(P) P(A) \quad \text{on } \mathcal{P}'$$

- ▶ the **prior** likelihood function lik can describe the information from past observations, or subjective beliefs (interpreted as the information from *virtual* past observations)

hierarchical model

- ▶ the set \mathcal{P} of probability measures and the likelihood function lik on \mathcal{P} can be interpreted as the two levels of a **hierarchical model** of the reality under consideration
- ▶ when an event $A \in \mathcal{A}$ is observed, the hierarchical model can be updated as follows:

$$\begin{aligned}\mathcal{P} &\rightsquigarrow \mathcal{P}' = \{P(\cdot | A) : P \in \mathcal{P}, P(A) > 0\} \\ lik &\rightsquigarrow lik'(P') \propto \sup_{P \in \mathcal{P} : P(\cdot | A) = P'} lik(P) P(A) \quad \text{on } \mathcal{P}'\end{aligned}$$

- ▶ the **prior** likelihood function lik can describe the information from past observations, or subjective beliefs (interpreted as the information from *virtual* past observations)
- ▶ the penalty term in penalized likelihood methods can often be interpreted as a prior lik

hierarchical model

- ▶ the set \mathcal{P} of probability measures and the likelihood function lik on \mathcal{P} can be interpreted as the two levels of a **hierarchical model** of the reality under consideration
- ▶ when an event $A \in \mathcal{A}$ is observed, the hierarchical model can be updated as follows:

$$\begin{aligned}\mathcal{P} &\rightsquigarrow \mathcal{P}' = \{P(\cdot | A) : P \in \mathcal{P}, P(A) > 0\} \\ lik &\rightsquigarrow lik'(P') \propto \sup_{P \in \mathcal{P} : P(\cdot | A) = P'} lik(P) P(A) \quad \text{on } \mathcal{P}'\end{aligned}$$

- ▶ the **prior** likelihood function lik can describe the information from past observations, or subjective beliefs (interpreted as the information from *virtual* past observations)
- ▶ the penalty term in penalized likelihood methods can often be interpreted as a prior lik
- ▶ the choice of a prior lik seems better supported by intuition than the choice of a prior probability measure: in particular, a constant lik describes the case of no information (**complete ignorance**)

imprecise probability

- ▶ the uncertain knowledge about the value $g(P)$ of a function $g : \mathcal{P} \rightarrow \mathcal{G}$ is described by the **profile** likelihood function

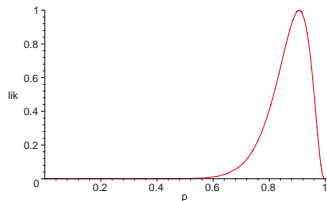
$$lik_g(\gamma) \propto \sup_{P \in \mathcal{P} : g(P) = \gamma} lik(P) \quad \text{on } \mathcal{G}$$

imprecise probability

- ▶ the uncertain knowledge about the value $g(P)$ of a function $g : \mathcal{P} \rightarrow \mathcal{G}$ is described by the **profile** likelihood function

$$lik_g(\gamma) \propto \sup_{P \in \mathcal{P} : g(P) = \gamma} lik(P) \quad \text{on } \mathcal{G}$$

- ▶ example: profile likelihood function for the probability p of observing at least 3 successes in the next 5 experiments (Bernoulli trials), after having observed 38 successes in 50 experiments

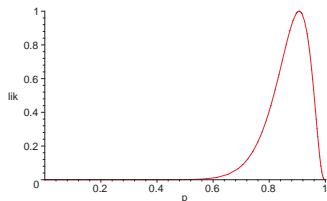


imprecise probability

- ▶ the uncertain knowledge about the value $g(P)$ of a function $g : \mathcal{P} \rightarrow \mathcal{G}$ is described by the **profile** likelihood function

$$lik_g(\gamma) \propto \sup_{P \in \mathcal{P} : g(P) = \gamma} lik(P) \quad \text{on } \mathcal{G}$$

- ▶ example: profile likelihood function for the probability p of observing at least 3 successes in the next 5 experiments (Bernoulli trials), after having observed 38 successes in 50 experiments



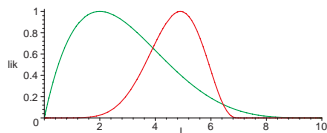
- ▶ *normalized* likelihood functions are a possible interpretation of membership functions of fuzzy sets: in this sense, the hierarchical model is a **fuzzy probability** measure, and the above graph shows the membership function of a fuzzy probability value

likelihood-based decisions

- ▶ a decision problem is described by a **loss function**
 $L : \mathcal{P} \times \mathcal{D} \rightarrow [0, \infty)$, where $L(P, d)$ is the loss incurred by making the decision d , according to the probabilistic model P

likelihood-based decisions

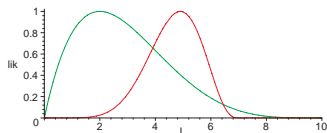
- ▶ a decision problem is described by a **loss function**
 $L : \mathcal{P} \times \mathcal{D} \rightarrow [0, \infty)$, where $L(P, d)$ is the loss incurred by making the decision d , according to the probabilistic model P
- ▶ example: profile likelihood functions for the losses $L(P, d_1)$ and $L(P, d_2)$ (i.e., membership functions for the fuzzy losses of d_1 and d_2)



likelihood-based decisions

- ▶ a decision problem is described by a **loss function**
 $L : \mathcal{P} \times \mathcal{D} \rightarrow [0, \infty)$, where $L(P, d)$ is the loss incurred by making the decision d , according to the probabilistic model P

- ▶ example: profile likelihood functions for the losses $L(P, d_1)$ and $L(P, d_2)$ (i.e., membership functions for the fuzzy losses of d_1 and d_2)



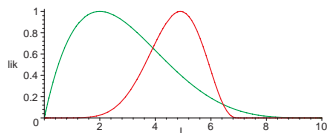
- ▶ maximum likelihood estimation leads to the MLD criterion:

$$\text{minimize } L(\hat{P}_{ML}, d)$$

likelihood-based decisions

- ▶ a decision problem is described by a **loss function**
 $L : \mathcal{P} \times \mathcal{D} \rightarrow [0, \infty)$, where $L(P, d)$ is the loss incurred by making the decision d , according to the probabilistic model P

- ▶ example: profile likelihood functions for the losses $L(P, d_1)$ and $L(P, d_2)$ (i.e., membership functions for the fuzzy losses of d_1 and d_2)



- ▶ maximum likelihood estimation leads to the MLD criterion:

$$\text{minimize } L(\hat{P}_{ML}, d)$$

- ▶ the only likelihood-based decision criterion satisfying some basic properties is the **MPL criterion** with $\alpha \in (0, \infty)$:

$$\text{minimize } \sup_{P \in \mathcal{P}} \text{lik}(P)^\alpha L(P, d)$$

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
 $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$,
 $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
$$L(P_0, d_0) = 0 \quad \text{and} \quad L(P_i, d_0) = 1 \quad \text{for all } i \in \{1, \dots, n\},$$
$$L(P_0, d_1) = 1 \quad \text{and} \quad L(P_i, d_1) = 0 \quad \text{for all } i \in \{1, \dots, n\},$$
 - ▶ **likelihood function** lik on \mathcal{P} with $lik(P_0) = c lik(P_i)$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
likelihood-based decision criterion $\Rightarrow d_0$ optimal

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
 $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$,
 $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,
 - ▶ **likelihood function** lik on \mathcal{P} with $lik(P_0) = c lik(P_i)$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
likelihood-based decision criterion $\Rightarrow d_0$ optimal
 - ▶ **probability measure** π on \mathcal{P} with $\pi\{P_0\} = c \pi\{P_i\}$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
Bayesian decision criterion $\Rightarrow d_1$ optimal when n is large enough
(*many bad probabilistic models make a good one*)

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
 $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$,
 $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,
 - ▶ **likelihood function** lik on \mathcal{P} with $lik(P_0) = c lik(P_i)$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
likelihood-based decision criterion $\Rightarrow d_0$ optimal
 - ▶ **probability measure** π on \mathcal{P} with $\pi\{P_0\} = c \pi\{P_i\}$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
Bayesian decision criterion $\Rightarrow d_1$ optimal when n is large enough
(*many bad probabilistic models make a good one*)
- ▶ in the Bayesian approach the probabilistic models are handled as possible “states of the world” (in particular, they are considered *mutually exclusive*)

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
 $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$,
 $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,
 - ▶ **likelihood function** lik on \mathcal{P} with $lik(P_0) = c lik(P_i)$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
likelihood-based decision criterion $\Rightarrow d_0$ optimal
 - ▶ **probability measure** π on \mathcal{P} with $\pi\{P_0\} = c \pi\{P_i\}$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
Bayesian decision criterion $\Rightarrow d_1$ optimal when n is large enough
(*many bad probabilistic models make a good one*)
- ▶ in the Bayesian approach the probabilistic models are handled as possible “states of the world” (in particular, they are considered *mutually exclusive*)
- ▶ basic advantage of the hierarchical model over

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
 $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$,
 $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,
 - ▶ **likelihood function** lik on \mathcal{P} with $lik(P_0) = c lik(P_i)$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
likelihood-based decision criterion $\Rightarrow d_0$ optimal
 - ▶ **probability measure** π on \mathcal{P} with $\pi\{P_0\} = c \pi\{P_i\}$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
Bayesian decision criterion $\Rightarrow d_1$ optimal when n is large enough
(*many bad probabilistic models make a good one*)
- ▶ in the Bayesian approach the probabilistic models are handled as possible “states of the world” (in particular, they are considered *mutually exclusive*)
- ▶ basic advantage of the hierarchical model over
 - ▶ the precise Bayesian model: the ability to describe the state of **complete ignorance**

comparison of hierarchical and Bayesian models

- ▶ example: $\mathcal{P} = \{P_0, P_1, \dots, P_n\}$ and $\mathcal{D} = \{d_0, d_1\}$, with
 $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$,
 $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,
 - ▶ **likelihood function** lik on \mathcal{P} with $lik(P_0) = c lik(P_i)$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
likelihood-based decision criterion $\Rightarrow d_0$ optimal
 - ▶ **probability measure** π on \mathcal{P} with $\pi\{P_0\} = c \pi\{P_i\}$ for a $c > 1$ and all $i \in \{1, \dots, n\}$:
Bayesian decision criterion $\Rightarrow d_1$ optimal when n is large enough
(*many bad probabilistic models make a good one*)
- ▶ in the Bayesian approach the probabilistic models are handled as possible “states of the world” (in particular, they are considered *mutually exclusive*)
- ▶ basic advantage of the hierarchical model over
 - ▶ the precise Bayesian model: the ability to describe the state of **complete ignorance**
 - ▶ the imprecise Bayesian model: the ability to **get out** of the state of complete ignorance

hierarchical model as a generalization of IP

- ▶ the **imprecise Bayesian model** can be interpreted as a group of precise Bayesian experts deciding by unanimity: experts are excluded from the group only if they gave deterministically wrong forecasts (that is, they assigned probability 0 to the observed event), otherwise they are always considered as fully credible (independently of the quality of their past forecasts)

hierarchical model as a generalization of IP

- ▶ the **imprecise Bayesian model** can be interpreted as a group of precise Bayesian experts deciding by unanimity: experts are excluded from the group only if they gave deterministically wrong forecasts (that is, they assigned probability 0 to the observed event), otherwise they are always considered as fully credible (independently of the quality of their past forecasts)
- ▶ in the **hierarchical model** the credibility of the experts depends on the relative quality of their past forecasts: the higher the credibility, the larger the influence on the decision making

hierarchical model as a generalization of IP

- ▶ the **imprecise Bayesian model** can be interpreted as a group of precise Bayesian experts deciding by unanimity: experts are excluded from the group only if they gave deterministically wrong forecasts (that is, they assigned probability 0 to the observed event), otherwise they are always considered as fully credible (independently of the quality of their past forecasts)
- ▶ in the **hierarchical model** the credibility of the experts depends on the relative quality of their past forecasts: the higher the credibility, the larger the influence on the decision making
- ▶ in particular, for the imprecise Bayesian model the state of **complete ignorance** corresponds to a group of experts who are absolutely certain of different things (there is no lack of information: on the contrary, there is plenty of contradictory information), while for the hierarchical model the state of complete ignorance corresponds to the lack of information for evaluating the credibility of these experts

robustness

- ▶ the **updating** of the hierarchical model is more robust than the updating of the imprecise Bayesian model

robustness

- ▶ the **updating** of the hierarchical model is more robust than the updating of the imprecise Bayesian model
- ▶ example: $\Omega = \{a, b, c\}$ and $X = I_{\{a\}} - I_{\{b\}}$,
 $E(X) = 0 \Rightarrow E(X | \{a, b\}) = 0$, but

robustness

- ▶ the **updating** of the hierarchical model is more robust than the updating of the imprecise Bayesian model
- ▶ example: $\Omega = \{a, b, c\}$ and $X = I_{\{a\}} - I_{\{b\}}$,
 $E(X) = 0 \Rightarrow E(X | \{a, b\}) = 0$, but
 - ▶ **imprecise Bayesian model:**
 $-\varepsilon \leq E(X) \leq \varepsilon \Rightarrow -1 \leq E(X | \{a, b\}) \leq 1$ for all $\varepsilon > 0$

robustness

- ▶ the **updating** of the hierarchical model is more robust than the updating of the imprecise Bayesian model

- ▶ example: $\Omega = \{a, b, c\}$ and $X = I_{\{a\}} - I_{\{b\}}$,
 $E(X) = 0 \Rightarrow E(X | \{a, b\}) = 0$, but

- ▶ **imprecise Bayesian model:**

$$-\varepsilon \leq E(X) \leq \varepsilon \Rightarrow -1 \leq E(X | \{a, b\}) \leq 1 \quad \text{for all } \varepsilon > 0$$

- ▶ **hierarchical model:**

profile likelihood functions
for $E(X | \{a, b\})$ when

$-\varepsilon \leq E(X) \leq \varepsilon$, for

$\varepsilon = 0.001$ and $\varepsilon = 0.01$

