Independence and Combination of Belief Functions

Marco Cattaneo Department of Statistics, LMU Munich cattaneo@stat.uni-muenchen.de

2 June 2010

Let x be a categorical variable taking values in the *finite* set $\mathcal{X} \neq \emptyset$.

Let x be a categorical variable taking values in the *finite* set $\mathcal{X} \neq \emptyset$.

In (Bayesian) probability theory, information about the uncertain value of x is described by the probability distribution of a random variable X taking values in \mathcal{X} .

Let x be a categorical variable taking values in the *finite* set $\mathcal{X} \neq \emptyset$.

In (Bayesian) probability theory, information about the uncertain value of x is described by the probability distribution of a random variable X taking values in \mathcal{X} .

In (Dempster-Shafer) *belief functions theory*, information about the uncertain value of x is described by the probability distribution of a **random subset** S of \mathcal{X} , with $S \neq \emptyset$ a.s.

Let x be a categorical variable taking values in the *finite* set $\mathcal{X} \neq \emptyset$.

In (Bayesian) probability theory, information about the uncertain value of x is described by the probability distribution of a random variable X taking values in \mathcal{X} .

In (Dempster-Shafer) *belief functions theory*, information about the uncertain value of x is described by the probability distribution of a **random subset** S of \mathcal{X} , with $S \neq \emptyset$ a.s.

Each value $A \subseteq \mathcal{X}$ of S is interpreted as " $x \in A$ " (without any additional information about the value of x); random variables thus correspond to the case with |S| = 1 a.s.

Let x be a categorical variable taking values in the *finite* set $\mathcal{X} \neq \emptyset$.

In (Bayesian) probability theory, information about the uncertain value of x is described by the probability distribution of a random variable X taking values in \mathcal{X} .

In (Dempster-Shafer) *belief functions theory*, information about the uncertain value of x is described by the probability distribution of a **random subset** S of \mathcal{X} , with $S \neq \emptyset$ a.s.

Each value $A \subseteq \mathcal{X}$ of S is interpreted as " $x \in A$ " (without any additional information about the value of x); random variables thus correspond to the case with |S| = 1 a.s.

The interpretation of the probability distribution of S varies from author to author, but it is usually an *epistemic* interpretation.

Given a set $B \subseteq \mathcal{X}$, each value $A \subseteq \mathcal{X}$ of *S* falls into one of the following 3 categories:

- ► $A \subseteq B$ (S = A supports " $x \in B$ "),
- ► $A \not\subseteq B$ and $A \not\subseteq B^{\mathsf{C}}$ (S = A supports neither " $x \in B$ " nor " $x \notin B$ "),
- ► $A \subseteq B^{\mathsf{C}}$ (S = A supports " $x \notin B$ ").

Given a set $B \subseteq \mathcal{X}$, each value $A \subseteq \mathcal{X}$ of *S* falls into one of the following 3 categories:

- $A \subseteq B$ $(S = A \text{ supports } "x \in B"),$
- A ⊈ B and A ⊈ B^C (S = A supports neither "x ∈ B" nor "x ∉ B"),
 A ⊆ B^C (S = A supports "x ∉ B").

 $Bel(B) = P\{S \subseteq B\}$ is the probability that S supports " $x \in B$ ".

Given a set $B \subseteq \mathcal{X}$, each value $A \subseteq \mathcal{X}$ of *S* falls into one of the following 3 categories:

- ► $A \subseteq B$ (S = A supports " $x \in B$ "),
- A ⊈ B and A ⊈ B^C (S = A supports neither "x ∈ B" nor "x ∉ B"),
 A ⊆ B^C (S = A supports "x ∉ B").

 $Bel(B) = P\{S \subseteq B\}$ is the probability that S supports " $x \in B$ ". $Pl(B) = P\{S \subseteq B\} + P\{S \not\subseteq B \text{ and } S \not\subseteq B^{\mathsf{C}}\} = 1 - Bel(B^{\mathsf{C}})$ is the probability that S does not support " $x \notin B$ ".

Given a set $B \subseteq \mathcal{X}$, each value $A \subseteq \mathcal{X}$ of S falls into one of the following 3 categories:

- $A \subseteq B$ $(S = A \text{ supports } "x \in B"),$
- A ⊈ B and A ⊈ B^C (S = A supports neither "x ∈ B" nor "x ∉ B"),
 A ⊆ B^C (S = A supports "x ∉ B").

 $Bel(B) = P\{S \subseteq B\}$ is the probability that S supports " $x \in B$ ". $Pl(B) = P\{S \subseteq B\} + P\{S \not\subseteq B \text{ and } S \not\subseteq B^{C}\} = 1 - Bel(B^{C})$ is the probability that S does not support " $x \notin B$ ".

Bel, $Pl: 2^{\mathcal{X}} \to [0,1]$ are dual, monotonic set functions with $Bel \leq Pl$.

Given a set $B \subseteq \mathcal{X}$, each value $A \subseteq \mathcal{X}$ of *S* falls into one of the following 3 categories:

- $A \subseteq B$ $(S = A \text{ supports } "x \in B"),$
- A ⊈ B and A ⊈ B^C (S = A supports neither "x ∈ B" nor "x ∉ B"),
 A ⊆ B^C (S = A supports "x ∉ B").

 $Bel(B) = P\{S \subseteq B\}$ is the probability that S supports " $x \in B$ ". $Pl(B) = P\{S \subseteq B\} + P\{S \not\subseteq B \text{ and } S \not\subseteq B^{C}\} = 1 - Bel(B^{C})$ is the probability that S does not support " $x \notin B$ ".

 $Bel, Pl : 2^{\mathcal{X}} \to [0, 1]$ are dual, monotonic set functions with $Bel \leq Pl$. $Bel = Pl \iff Bel$ is additive $\Leftrightarrow Pl$ is additive $\Leftrightarrow |S| = 1$ a.s.

Bel and Pl correspond to coherent *lower and upper probabilities*, respectively, in the theory of Walley (1991).

Bel and Pl correspond to coherent *lower and upper probabilities*, respectively, in the theory of Walley (1991).

However, the connection with imprecise probabilities can be misleading: for example, if $\mathcal{X} = \{e, \neg e\}$, and on the basis of completely different approaches two experts assign the probabilities 0.8 and 0.9, respectively, to the event x = e, then

Bel and Pl correspond to coherent *lower and upper probabilities*, respectively, in the theory of Walley (1991).

However, the connection with imprecise probabilities can be misleading: for example, if $\mathcal{X} = \{e, \neg e\}$, and on the basis of completely different approaches two experts assign the probabilities 0.8 and 0.9, respectively, to the event x = e, then

the combined (precise or imprecise) probability of x = e will be in or around the interval [0.8, 0.9],

Bel and Pl correspond to coherent *lower and upper probabilities*, respectively, in the theory of Walley (1991).

However, the connection with imprecise probabilities can be misleading: for example, if $\mathcal{X} = \{e, \neg e\}$, and on the basis of completely different approaches two experts assign the probabilities 0.8 and 0.9, respectively, to the event x = e, then

- the combined (precise or imprecise) probability of x = e will be in or around the interval [0.8, 0.9],
- while the combined belief in x = e will be $0.\overline{972}$ (using *Dempster's rule of combination*).

Bel and Pl correspond to coherent *lower and upper probabilities*, respectively, in the theory of Walley (1991).

However, the connection with imprecise probabilities can be misleading: for example, if $\mathcal{X} = \{e, \neg e\}$, and on the basis of completely different approaches two experts assign the probabilities 0.8 and 0.9, respectively, to the event x = e, then

- the combined (precise or imprecise) probability of x = e will be in or around the interval [0.8, 0.9],
- ▶ while the combined belief in x = e will be 0.972 (using Dempster's rule of combination).

Bel and *Pl* are descriptions of the *support provided by the available evidence*, while a (precise or imprecise) probability distribution is the description of an *equilibrium*.

Bel and Pl correspond to coherent *lower and upper probabilities*, respectively, in the theory of Walley (1991).

However, the connection with imprecise probabilities can be misleading: for example, if $\mathcal{X} = \{e, \neg e\}$, and on the basis of completely different approaches two experts assign the probabilities 0.8 and 0.9, respectively, to the event x = e, then

- the combined (precise or imprecise) probability of x = e will be in or around the interval [0.8, 0.9],
- ▶ while the combined belief in x = e will be 0.972 (using Dempster's rule of combination).

Bel and *Pl* are descriptions of the *support provided by the available evidence*, while a (precise or imprecise) probability distribution is the description of an *equilibrium*.

In the above example, the probability ratios are multiplied (as if they were likelihood ratios): $\frac{0.8}{1-0.8} \times \frac{0.9}{1-0.9} = 36 = \frac{0.972}{1-0.972}$. In fact, *Bel* and *Pl* were rather interpreted as generalizations of *likelihood functions* or *fiducial probabilities* by Dempster and Shafer: see also Wiencierz (2009).

If the probability distributions of the random subsets S_1, \ldots, S_n of \mathcal{X} describe the information (about the uncertain value of x) obtained from n different sources, respectively, then the **combined information** is described by the probability distribution of $S_1 \cap \cdots \cap S_n$, which depends on the *joint probability distribution* of S_1, \ldots, S_n .

If the probability distributions of the random subsets S_1, \ldots, S_n of \mathcal{X} describe the information (about the uncertain value of x) obtained from n different sources, respectively, then the **combined information** is described by the probability distribution of $S_1 \cap \cdots \cap S_n$, which depends on the *joint probability distribution* of S_1, \ldots, S_n .

The *independence* of S_1, \ldots, S_n is often assumed, but is in general **incompatible** with the condition that $S_1 \cap \cdots \cap S_n \neq \emptyset$ a.s.

If the probability distributions of the random subsets S_1, \ldots, S_n of \mathcal{X} describe the information (about the uncertain value of x) obtained from n different sources, respectively, then the **combined information** is described by the probability distribution of $S_1 \cap \cdots \cap S_n$, which depends on the *joint probability distribution* of S_1, \ldots, S_n .

The *independence* of S_1, \ldots, S_n is often assumed, but is in general **incompatible** with the condition that $S_1 \cap \cdots \cap S_n \neq \emptyset$ a.s.

Dempster's rule of combination consists in assuming the independence of S_1, \ldots, S_n and **then** conditioning on $\{S_1 \cap \cdots \cap S_n \neq \emptyset\}$ (if possible). However, in general the conditional joint probability distribution neither has the right marginal distributions for S_1, \ldots, S_n , nor describes their independence.

If the probability distributions of the random subsets S_1, \ldots, S_n of \mathcal{X} describe the information (about the uncertain value of x) obtained from n different sources, respectively, then the **combined information** is described by the probability distribution of $S_1 \cap \cdots \cap S_n$, which depends on the *joint probability distribution* of S_1, \ldots, S_n .

The *independence* of S_1, \ldots, S_n is often assumed, but is in general **incompatible** with the condition that $S_1 \cap \cdots \cap S_n \neq \emptyset$ a.s.

Dempster's rule of combination consists in assuming the independence of S_1, \ldots, S_n and **then** conditioning on $\{S_1 \cap \cdots \cap S_n \neq \emptyset\}$ (if possible). However, in general the conditional joint probability distribution neither has the right marginal distributions for S_1, \ldots, S_n , nor describes their independence.

In the experts' example, after the conditioning, $S_1 = S_2$ a.s. with $P\{S_i = \{e\}\} = 0.\overline{972}$ and $P\{S_i = \{\neg e\}\} = 0.\overline{027}$.

If the probability distributions of the random subsets S_1, \ldots, S_n of \mathcal{X} describe the information (about the uncertain value of x) obtained from n different sources, respectively, then the **combined information** is described by the probability distribution of $S_1 \cap \cdots \cap S_n$, which depends on the *joint probability distribution* of S_1, \ldots, S_n .

The *independence* of S_1, \ldots, S_n is often assumed, but is in general **incompatible** with the condition that $S_1 \cap \cdots \cap S_n \neq \emptyset$ a.s.

Dempster's rule of combination consists in assuming the independence of S_1, \ldots, S_n and **then** conditioning on $\{S_1 \cap \cdots \cap S_n \neq \emptyset\}$ (if possible). However, in general the conditional joint probability distribution neither has the right marginal distributions for S_1, \ldots, S_n , nor describes their independence.

In the experts' example, after the conditioning, $S_1 = S_2$ a.s. with $P\{S_i = \{e\}\} = 0.\overline{972}$ and $P\{S_i = \{\neg e\}\} = 0.\overline{027}$.

Hence, Dempster's rule of combination can at best be considered as corresponding to an **approximation** of independence.

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

A typical solution in theories dealing with uncertainty is to select the *least* precise description of information (for instance by *entropy maximization*).

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

A typical solution in theories dealing with uncertainty is to select the *least* precise description of information (for instance by *entropy maximization*).

However, this approach has several problems, such as:

▶ there are many different definitions of "least precise" belief function,

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

A typical solution in theories dealing with uncertainty is to select the *least* precise description of information (for instance by *entropy maximization*).

However, this approach has several problems, such as:

- ▶ there are many different definitions of "least precise" belief function,
- for each of them the least precise belief function is in general *not* unique,

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

A typical solution in theories dealing with uncertainty is to select the *least* precise description of information (for instance by *entropy maximization*).

However, this approach has several problems, such as:

- ▶ there are many different definitions of "least precise" belief function,
- for each of them the least precise belief function is in general *not* unique,
- the selection of a whole belief function can be *computationally too demanding*,

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

A typical solution in theories dealing with uncertainty is to select the *least* precise description of information (for instance by *entropy maximization*).

However, this approach has several problems, such as:

- ▶ there are many different definitions of "least precise" belief function,
- for each of them the least precise belief function is in general *not* unique,
- the selection of a whole belief function can be computationally too demanding,
- ▶ in general the condition that $S_1 \cap \cdots \cap S_n \neq \emptyset$ a.s. *cannot be satisfied*.

When no dependence structure is assumed for S_1, \ldots, S_n , there are in general many possible probability distributions for $S_1 \cap \cdots \cap S_n$.

A typical solution in theories dealing with uncertainty is to select the *least* precise description of information (for instance by *entropy maximization*).

However, this approach has several problems, such as:

- ▶ there are many different definitions of "least precise" belief function,
- for each of them the least precise belief function is in general *not* unique,
- the selection of a whole belief function can be computationally too demanding,
- ▶ in general the condition that $S_1 \cap \cdots \cap S_n \neq \emptyset$ a.s. *cannot be satisfied*.

In the experts' example, $P\{S_1 \cap S_2 = \varnothing\} \in [0.1, 0.3]$ for all possible joint probability distributions of S_1, S_2 .

The new idea in Cattaneo (2010) is to *approximate* by a belief function the set function $F : 2^{\mathcal{X}} \to [0, 1]$ that is **pointwise least precise**: Fassigns to each $B \subseteq \mathcal{X}$ the *minimum* of $P\{S_1 \cap \cdots \cap S_n \subseteq B\}$ over all possible joint probability distributions of S_1, \ldots, S_n (that is, F is a *lower envelope*).

The new idea in Cattaneo (2010) is to approximate by a belief function the set function $F : 2^{\mathcal{X}} \to [0, 1]$ that is **pointwise least precise**: Fassigns to each $B \subseteq \mathcal{X}$ the minimum of $P\{S_1 \cap \cdots \cap S_n \subseteq B\}$ over all possible joint probability distributions of S_1, \ldots, S_n (that is, F is a lower envelope).

In particular, the **minimal conflict** $F(\emptyset)$ is a very interesting measure of disagreement among belief functions: see also Cattaneo (2003).

The new idea in Cattaneo (2010) is to approximate by a belief function the set function $F : 2^{\mathcal{X}} \to [0, 1]$ that is **pointwise least precise**: Fassigns to each $B \subseteq \mathcal{X}$ the minimum of $P\{S_1 \cap \cdots \cap S_n \subseteq B\}$ over all possible joint probability distributions of S_1, \ldots, S_n (that is, F is a lower envelope).

In particular, the **minimal conflict** $F(\emptyset)$ is a very interesting measure of disagreement among belief functions: see also Cattaneo (2003).

For each $B \subseteq \mathcal{X}$, the quantity

$$\max_{\substack{B_1,\ldots,B_n\subseteq \mathcal{X}:\\B_1\cap\cdots\cap B_n\subseteq B}} (P\{S_1\subseteq B_1\}+\cdots+P\{S_n\subseteq B_n\})+1-n$$

is a simple *lower approximation* of F(B), which is exact when $n \le 2$, as follows from a result by Strassen (1965).

The new idea in Cattaneo (2010) is to approximate by a belief function the set function $F : 2^{\mathcal{X}} \to [0, 1]$ that is **pointwise least precise**: Fassigns to each $B \subseteq \mathcal{X}$ the minimum of $P\{S_1 \cap \cdots \cap S_n \subseteq B\}$ over all possible joint probability distributions of S_1, \ldots, S_n (that is, F is a lower envelope).

In particular, the **minimal conflict** $F(\emptyset)$ is a very interesting measure of disagreement among belief functions: see also Cattaneo (2003).

For each $B \subseteq \mathcal{X}$, the quantity

$$\max_{\substack{B_1,\ldots,B_n\subseteq \mathcal{X}:\\B_1\cap\cdots\cap B_n\subseteq B}} (P\{S_1\subseteq B_1\}+\cdots+P\{S_n\subseteq B_n\})+1-n$$

is a simple *lower approximation* of F(B), which is exact when $n \le 2$, as follows from a result by Strassen (1965).

In the experts' example, $F(\emptyset) = 0.1$, $F(\{e\}) = 0.9$, $F(\{\neg e\}) = 0.2$, and $F(\mathcal{X}) = 1$. Hence, there is a joint probability distribution of S_1, S_2 with $F(B) = P\{S_1 \cap S_2 \subseteq B\}$ for all $B \subseteq \mathcal{X}$, but $P\{S_1 \cap S_2 = \emptyset\} = 0.1$.

references

Cattaneo (2003). Combining belief functions issued from dependent sources. In *ISIPTA '03*, Carleton Scientific, pp. 133–147.

Cattaneo (2010). Belief functions combination without the assumption of independence of the information sources. *To appear*.

Strassen (1965). The existence of probability measures with given marginals. *Ann. Math. Stat.* 36(2):423–439.

Walley (1991). *Statistical Reasoning with Imprecise Probabilities*. Chapman and Hall.

Wiencierz (2009). Arthur P. Dempster's Generalized Inference Theory. Master's thesis, LMU Munich.