The likelihood approach to statistics as a theory of imprecise probability

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- ▶ log ^{lik(P₁)}/_{lik(P₂)} is the information for discrimination (or weight of evidence) in favor of P₁ against P₂
- ▶ in particular, a constant *lik* describes the case of **no information** for discrimination among the probabilistic models in *P*

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- the prior likelihood function *lik* can describe the information from past observations, or subjective beliefs (interpreted as the information from *virtual* past observations)
- the penalty term in penalized likelihood methods can often be interpreted as a prior *lik*
- the choice of a prior *lik* seems better supported by intuition than the choice of a prior probability measure: in particular, a constant *lik* describes the case of no information (complete ignorance)

imprecise probability

► the uncertain knowledge about the value g(P) of a function g : P → G is described by the profile likelihood function

$$\mathit{lik}_{g}(\gamma) \propto \sup_{P \in \mathcal{P} : g(P) = \gamma} \mathit{lik}(P) \hspace{0.2cm} ext{on} \hspace{0.2cm} \mathcal{G}$$

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normalized likelihood functions are a possible interpretation of membership functions of fuzzy sets: in this sense, the hierarchical model is a fuzzy probability measure, and the above graph shows the membership function of a fuzzy probability value

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► the only likelihood-based decision criterion satisfying some basic properties is the MPL criterion with α ∈ (0,∞):

minimize $\sup_{P \in \mathcal{P}} lik(P)^{\alpha} L(P, d)$

▶ example:
$$\mathcal{P} = \{P_0, P_1, \dots, P_n\}$$
 and $\mathcal{D} = \{d_0, d_1\}$, with $L(P_0, d_0) = 0$ and $L(P_i, d_0) = 1$ for all $i \in \{1, \dots, n\}$, $L(P_0, d_1) = 1$ and $L(P_i, d_1) = 0$ for all $i \in \{1, \dots, n\}$,

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 - ▶ likelihood function *lik* on \mathcal{P} with $lik(P_0) = c \ lik(P_i)$ for a c > 1and all $i \in \{1, ..., n\}$:

likelihood-based decision criterion \Rightarrow d₀ optimal

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 - ▶ likelihood function lik on P with lik(P₀) = c lik(P_i) for a c > 1 and all i ∈ {1,...,n}: likelihood-based decision criterion ⇒ d₀ optimal
 - Probability measure π on P with π{P₀} = c π{P_i} for a c > 1 and all i ∈ {1,...,n}: Bayesian decision criterion ⇒ d₁ optimal when n is large enough

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•	the imprecise Bayesian model:	the ability to get out of the state of complete ignorance