# **M-Estimation with Imprecise Data**

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> ISIPTA '15, Pescara, Italy 20 July 2015

### precise case

**data**:  $X_1, ..., X_n \in \mathcal{X}$  i.i.d. with (unknown) distribution  $P_X$  **goal**: estimating the value(s)  $\theta_0$  of  $\theta \in \Theta$  that minimize(s)  $\underbrace{L(P_X, \theta)}_{\text{loss/distance}} \stackrel{\text{e.g.}}{=} \underbrace{E_{P_X} \left[\rho(X, \theta)\right]}_{\text{risk}} \stackrel{\text{e.g.}}{=} \underbrace{E_{P_X} \left[(X - \theta)^2\right]}_{\text{mean squared error: }\theta_0 = E_{P_X}[X]}$  **ML estimate** (nonparametric) of  $L(P_X, \cdot)$ : the function  $L(\hat{P}_X, \cdot)$  obtained by plugging in the empirical distribution of the data  $\hat{P}_X$  **ML decision** (Cattaneo, 2013): the estimate(s)  $\hat{\theta}_0$  that minimize(s)  $\underbrace{L(\hat{P}_X, \theta)}_{\hat{\theta}_0: \text{ minimum distance estimator}} \stackrel{\text{e.g.}}{=} \underbrace{\frac{1}{n} \sum_{i=1}^n \rho(X_i, \theta)}_{\hat{\theta}_0: \text{ M-estimator}} \stackrel{\text{e.g.}}{=} \underbrace{\frac{1}{n} \sum_{i=1}^n (X_i - \theta)^2}_{\hat{\theta}_0 = \frac{1}{n} \sum_{i=1}^n X_i: \text{ least squares estimator}}$  **asymptotic consistency**: under some regularity conditions (Wolfowitz, 1957; Huber, 1964),  $\hat{\theta}_0 \xrightarrow{\text{a.s.}}_{n \to \infty} \theta_0$ 

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### imprecise case

## **data**: $S_1, \ldots, S_n \subseteq \mathcal{X}$ i.i.d. with (unknown) distribution $P_S$ , such that $X_i \in S_i$

- the distribution  $P_S$  of the imprecise data only partially determines the distribution  $P_X$  of the (unobservable) precise data: let  $[P_S]$  be the set of all distributions  $P_X$  compatible with  $P_S$  (in the sense that  $X_i \in S_i$  is possible)
- assumptions reducing  $[P_S]$  are also possible (e.g., all "beta distributions" on interval data) for the ML decision, but not for the black-box approach to estimation (see definitions below)

**black-box approach** (e.g., Ferson et al., 2007): since  $X_1, \ldots, X_n$  are only known to lie in  $S_1, \ldots, S_n$ , replace the estimate  $\hat{\theta}_0(X_1, \ldots, X_n)$  with (the convex hull of) the set of estimates

$$\left\{ \hat{ heta}_0(X_1,\ldots,X_n): X_i\in S_i 
ight\}$$

**ML estimate** (nonparametric) of  $L(P_X, \cdot)$ : usually not unique, it corresponds to the the set  $\{L(P_X, \cdot) : P_X \in [\hat{P}_S]\}$  of all functions obtained by plugging in the distributions  $P_X$ compatible with the empirical distribution of the (imprecise) data  $\hat{P}_S$ 

**ML decision**: the estimate(s)  $\hat{\theta}_0$  that minimize(s)

$$\left\{L(P_X,\theta): P_X \in [\hat{P}_S]\right\} \stackrel{\text{e.g.}}{=} \underbrace{\left\{E_{P_X}\left[\rho(X,\theta)\right]: P_X \in [\hat{P}_S]\right\}}_{=co\left\{\frac{1}{n}\sum_{i=1}^n \rho(X_i,\theta): X_i \in S_i\right\}} \stackrel{\text{e.g.}}{=} \underbrace{\left\{E_{P_X}\left[(X-\theta)^2\right]: P_X \in [\hat{P}_S]\right\}}_{=co\left\{\frac{1}{n}\sum_{i=1}^n (X_i-\theta)^2: X_i \in S_i\right\}}$$

asymptotic consistency, depending on the definition of minimum: under some regularity conditions (and possibly "smoothing corrections"),

### pointwise dominance:

$$\hat{\theta}_0 \xrightarrow[n \to \infty]{\text{arg min}_{\theta \in \Theta}} L(P_X, \theta) : P_X \in [P_S] \}$$

- pointwise dominance ("maximality") and black-box approach ("E-admissibility") have the same limit, called sharp collection region by Schollmeyer and Augustin (2015)
- e.g., set of undominated regression functions of LIR approach (Cattaneo and Wiencierz, 2012, 2014), which uses interval dominance for computational reasons

### minimax:

$$\hat{\theta}_0 \xrightarrow[n \to \infty]{\text{a.s.}} \operatorname{arg\,min}_{\theta \in \Theta} \operatorname{max}_{P_X \in [P_S]} L(P_X, \theta)$$

- estimate and limit are usually unique, which greatly simplifies computation, description, and interpretation of the results: see logistic regression example below
- e.g., minimax SVR estimate (Utkin and Coolen, 2011; Wiencierz and Cattaneo, 2015), or LRM regression function of LIR approach (Cattaneo and Wiencierz, 2012, 2014)

### minimin:

$$\hat{\theta}_0 \xrightarrow[n \to \infty]{a.s.} \{ \theta \in \Theta : L(P_X, \theta) = 0, P_X \in [P_S] \}$$

- in parametric models the limit is the identification region (Manski, 2003) of the parameter  $\theta$  (when L corresponds to a distance between distributions), called sharp marrow region by Schollmeyer and Augustin (2015): see parametric model example below
- e.g., minimin SVR estimate (Utkin and Coolen, 2011; Wiencierz and Cattaneo, 2015)

- **precise data**:  $X_1, ..., X_n \in \mathcal{X} = \{A, B, C\}$ i.i.d. with (unknown) distribution  $P_X = (p_A, p_B, p_C)$
- **parametric model** (represented by <u>blue line</u>):  $p_B = p_C = \frac{1-\theta}{2}$  with  $\theta = p_A \in \Theta = [0, 1]$ , i.e.,  $P_{X,\theta} = (\theta, \frac{1-\theta}{2}, \frac{1-\theta}{2})$  with  $\theta \in [0, 1]$
- **loss**  $L(P_X, \theta)$ : Euclidean distance between  $P_X$ and  $P_{X,\theta}$

**empirical distribution** of precise data:  $\hat{P}_X = \left(\frac{n_A}{n}, \frac{n_B}{n}, \frac{n_C}{n}\right)$ , where  $n_A, n_B, n_C$  are the count data of A, B, C, respectively

**ML decision** with precise data:  $\hat{\theta}_0 = \frac{n_A}{n}$ 

• asymptotic consistency:  $\hat{\theta}_0 \xrightarrow[n \to \infty]{a.s.} \theta$ 



•  $\hat{\theta}_0$  is also the parametric ML estimator: i.e., the M-estimator with the Kullback–Leibler divergence from  $P_X$  to  $P_{X,\theta}$  as loss  $L(P_X, \theta)$ 

**imprecise data**:  $S_1, ..., S_n \in \{\{A\}, \{B\}, \{C\}, \mathcal{X}\}$  i.i.d. with (unknown) distribution  $P_S = (q_A, q_B, q_C, q_{na})$  (i.e., data are either precisely observed, or missing), such that  $X_i \in S_i$ 

- $[P_S] = \{P_X : p_j \ge q_j \text{ for all } j \in \mathcal{X}\}$  is the set of all distributions  $P_X$  compatible with  $P_S = (q_A, q_B, q_C, q_{na})$
- e.g., the gray area represents the set  $[P_S]$  of all distributions  $P_X$  compatible with  $P_S = (0.1, 0.4, 0.2, 0.3)$

**empirical distribution** of imprecise data:  $\hat{P}_S = \left(\frac{n_A}{n}, \frac{n_B}{n}, \frac{n_C}{n}, \frac{n_{na}}{n}\right)$ , where  $n_A$ ,  $n_B$ ,  $n_C$ ,  $n_{na}$  are the count data of A, B, C, and missing, respectively

ML decision with imprecise data:

pointwise dominance:  $\hat{\theta}_0 = \begin{bmatrix} \frac{n_A}{n}, \frac{n_A + n_{na}}{n} \end{bmatrix}$ 

- asymptotic consistency:  $\hat{\theta}_0 \xrightarrow[n \to \infty]{a.s.} \{p_A : P_X \in [P_S]\}$  (represented by orange segment)
- $\hat{\theta}_0$  is also the convex hull of the set of estimates  $\left\{\hat{\theta}_0(X_1, \dots, X_n) : X_i \in S_i\right\}$  (black-box approach)

**minimax**: 
$$\hat{\theta}_0 = \frac{2}{3} \frac{n_A}{n} + \frac{1}{3} \left( \left( 1 - 2 \frac{n_B \vee n_C}{n} \right) \vee \frac{n_A}{n} \right)$$

- asymptotic consistency:  $\hat{\theta}_0 \xrightarrow[n \to \infty]{a.s.} \frac{2}{3} q_A + \frac{1}{3} (1 2(q_B \lor q_C))$  (represented by <u>black point</u>)
- $\hat{\theta}_0$  changes if the Euclidean distance  $L(P_X, \theta)$  between  $P_X$  and  $P_{X,\theta}$  is replaced by the Kullback– Leibler divergence from  $P_X$  to  $P_{X,\theta}$  (while this is not the case for the other two definitions of minimum)

minimin: 
$$\hat{\theta}_0 = \left[\frac{n_A}{n}, \left(1 - 2\frac{n_B \vee n_C}{n}\right) \vee \frac{n_A}{n}\right]$$

- asymptotic consistency:  $\hat{\theta}_0 \xrightarrow[n \to \infty]{a.s.} \{p_A : P_{X,\theta} \in [P_S]\}$  (represented by red segment)
- $\hat{\theta}_0$  estimates the set of all  $\theta$  compatible with the distribution of the (imprecise) data: this is often the goal when the parametric model is assumed to be true

precise data:  $(X_1, Y_1), \ldots, (X_{468}, Y_{468}) \in \mathbb{R} \times \{0, 1\}$  i.i.d. with (unknown) distribution  $P_{(X,Y)}$ , describing the presence (Y = 1) or absence (Y = 0) of marine debris in the gastrointestinal system of a green turtle that died at time X

**logistic regression**: estimates  $(\hat{\alpha}, \hat{\beta})$  of the regression parameters  $(\alpha, \beta) = \theta \in \Theta = \mathbb{R}^2$ are obtained by minimizing

$$\begin{split} L(\hat{P}_{(X,Y)},(\alpha,\beta)) &= \sum_{i=1}^{n} \left(Y_i \ln\left(1 + \exp(-\alpha - \beta X_i)\right) + (1 - Y_i) \ln\left(1 + \exp(\alpha + \beta X_i)\right)\right) \\ &= -\ln\prod_{i=1}^{n} \left(\frac{1}{1 + \exp(-\alpha - \beta X_i)}\right)^{Y_i} \left(1 - \frac{1}{1 + \exp(-\alpha - \beta X_i)}\right)^{1 - Y_i} \end{split}$$

•  $(\hat{\alpha}, \hat{\beta})$  are the parametric ML estimates when  $P(Y = 1 | X) = \frac{1}{1 + \exp(-\alpha - \beta X)}$  is assumed

• of particular interest is the question if the probability of debris ingestion increased over time ( $\beta > 0$ ) or not ( $\beta \leq 0$ )

imprecise data:  $[X_1, \overline{X}_1] \times \{Y_1\}, ..., [X_{468}, \overline{X}_{468}] \times \{Y_{468}\} \subset \mathbb{R} \times \{0, 1\}$  i.i.d. with (unknown) distribution  $P_{[X,\overline{X}] \times \{Y\}}$  (Schuyler et al., 2014)

**minimax logistic regression**: estimates  $(\hat{\alpha}_m, \hat{\beta}_m)$  are obtained by minimizing

$$\max_{\hat{P}_{(X,Y)}\in[\hat{P}_{[\underline{X},\overline{X}]\times\{Y\}}]} L(\hat{P}_{(X,Y)}, (\alpha, \beta)) = \begin{cases} L(\hat{P}_{(Y\overline{X}+(1-Y)\underline{X},Y)}, (\alpha, \beta)) & \text{if } \beta \leq 0 \\ L(\hat{P}_{(Y\underline{X}+(1-Y)\overline{X},Y)}, (\alpha, \beta)) & \text{if } \beta \geq 0 \end{cases}$$

- computing the minimax logistic regression corresponds to computing two (standard) logistic regressions, with the two extreme cases for the precise X data:  $Y\overline{X} + (1 - Y)\underline{X}$ and  $Y \underline{X} + (1 - Y) \overline{X}$
- significant positivity of  $\hat{\beta}_m$  (with pvalue  $\approx$  0.001) in the logistic regression with worst-case precise Xdata (i.e.,  $YX + (1-Y)\overline{X}$ ) should imply also the significant positivity of  $\hat{\beta}$  in the logistic regression with the true precise X data: that is, the ingestion of marine debris by green



minimax logistic regression